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PROPERTIES OF CERTAIN HOMOGENEOUS LINEAR SUBSTITUTIONS.

BY HAROLD HILTON.

1. Professor Loewy has discussed* the properties of a homogeneous linear substitution A

$$x_i' = a_{i1}x_1 + a_{i2}x_2 + \cdots + a_{im}x_m \quad (i = 1, 2, \dots, m),$$

which has as an invariant

$$\sum_i \epsilon_{ik} x_i \bar{x}_i \equiv x_1 \bar{x}_1 + x_2 \bar{x}_2 + \cdots + x_k \bar{x}_k - x_{k+1} \bar{x}_{k+1} - \cdots - x_m \bar{x}_m,$$

where x, \bar{x} denote conjugate complex quantities, and $\epsilon_{ij} = 1$ when i, j are both $> k$ or both $\leq k$, and $\epsilon_{ij} = -1$ when one of i and j is $> k$ and the other is $\leq k$ ($m \geq k \geq 0$).

I shall call the substitution A *quasi-unitary* in this case ("unitary" if $k = m$).

If A , instead of being quasi-unitary, satisfies the conditions $a_{ij} = \epsilon_{ij} \bar{a}_{ji}$, A will be called *quasi-Hermitian* ("Hermitian" if $k = m$). For instance, the substitution with matrix

$$\begin{vmatrix} a & w & g & p \\ \bar{h} & b & f & q \\ \bar{g} & \bar{f} & c & r \\ -\bar{p} & -\bar{q} & -\bar{r} & s \end{vmatrix}$$

is quasi-Hermitian, if a, b, c, s are real ($k = 3, m = 4$).

The main interest of a quasi-Hermitian substitution lies in the fact that it bears a relation to a quasi-unitary substitution similar to that borne by a symmetric substitution to an orthogonal substitution. For instance, a quasi-Hermitian substitution is transformed by a quasi-unitary substitution into a quasi-Hermitian substitution, just as a symmetric substitution is transformed by an orthogonal substitution into a symmetric substitution;† and similar relations are developed in §§ 4 and 5.

But a quasi-Hermitian substitution has also properties analogous to important properties of a quasi-unitary substitution, as proved in §§ 2 and 3.

* Math. Annalen, 50 (1898), pp. 563, 564.

† Proc. London Math. Soc., 2, X (1911), p. 274.

2. Professor Loewy (loc. cit.) has pointed out that those invariant-factors (elementartheiler) of a quasi-unitary substitution, which are not of the form $(\lambda - \alpha)^a$ where $\alpha\bar{\alpha} = 1$, can be grouped into pairs of the type $(\lambda - \alpha)^a, (\lambda - \bar{\alpha}^{-1})^a$ where $\alpha\bar{\alpha} \neq 1$.* We have similarly:—*Those invariant-factors of a quasi-Hermitian substitution which are not of the form $(\lambda - \alpha)^a$ where α is real, can be grouped into pairs of the type $(\lambda - \alpha)^a, (\lambda - \bar{\alpha})^a$.*

For suppose that A is the quasi-Hermitian substitution

$$x_t' = a_{t1}x_1 + a_{t2}x_2 + \cdots + a_{tm}x_m \quad (t = 1, 2, \dots, m),$$

transformed by P^{-1} into the canonical substitution N ; so that $P^{-1}NP = A$. By a "canonical substitution" we mean a substitution of the type

$$x_t' = \lambda_t x_t + \beta_t x_{t+1} \quad (t = 1, 2, \dots, m),$$

where β_t is 0 or 1, and is certainly 0 if $\lambda_t \neq \lambda_{t+1}$. It is well known that every substitution is transformable into such a canonical substitution.†

Suppose that C is the Hermitian substitution

$$x_t' = c_{t1}x_1 + c_{t2}x_2 + \cdots + c_{tm}x_m \quad (t = 1, 2, \dots, m),$$

where

$$c_{ij} = \bar{c}_{ji} = \sum_{t=1}^m \epsilon_{tk} p_{ti} \bar{p}_{tj}.$$

Then we have (Proc. London Math. Soc., 2, X (1912), p. 282)

$$\lambda_i c_{ij} + \beta_{i-1} c_{i-1j} = \bar{\lambda}_j c_{ij} + \beta_{j-1} c_{ij-1}.$$

From this it follows, as in Mess. Math. (1912), p. 148, that, if $\lambda_i \neq \bar{\lambda}_j$, then $c_{ij} = 0$; but that if $\lambda_i = \bar{\lambda}_j$, then

$$c_{i-1j} = 0 \quad \text{when } \beta_{i-1} = 1 \quad \text{and} \quad \beta_{j-1} = 0,$$

$$c_{ij-1} = 0 \quad \text{when } \beta_{i-1} = 0 \quad \text{and} \quad \beta_{j-1} = 1,$$

$$c_{i-1j} = c_{ij-1} \quad \text{when } \beta_{i-1} = 1 \quad \text{and} \quad \beta_{j-1} = 1.$$

For example, if N is

$$x_1' = \alpha x_1 + x_2, \quad x_2' = \alpha x_2 + x_3, \quad x_3' = \alpha x_3; \quad x_4' = \alpha x_4 + x_5,$$

$$x_5' = \alpha x_5; \quad x_6' = \alpha x_6 + x_7, \quad x_7' = \alpha x_7; \quad x_8' = \alpha x_8,$$

where α is real, C has a matrix of the type

* See also Proc. London Math. Soc., 2, XI (1912), p. 97.

† See, for instance, Mess. Math. (1909), p. 24.

$$\begin{vmatrix} 0 & 0 & a & 0 & 0 & 0 & 0 & 0 \\ 0 & a & b & 0 & d & 0 & f & 0 \\ a & b & c & d & e & f & g & h \\ 0 & 0 & \bar{d} & 0 & i & 0 & k & 0 \\ 0 & \bar{d} & \bar{e} & i & j & k & l & m \\ 0 & 0 & \bar{f} & 0 & \bar{k} & 0 & n & 0 \\ 0 & \bar{f} & \bar{g} & \bar{k} & \bar{l} & n & p & q \\ 0 & 0 & \bar{h} & 0 & \bar{m} & 0 & \bar{q} & r \end{vmatrix},$$

a, b, c, i, j, n, p, r being real;
or again if N is

$$\left. \begin{aligned} x_1' &= \alpha x_1 + x_2, & x_2' &= \alpha x_2; & x_3' &= \alpha x_3; \\ x_4' &= \bar{\alpha} x_4 + x_5, & x_5' &= \bar{\alpha} x_5; & x_6' &= \bar{\alpha} x_6 \end{aligned} \right\}$$

c has a matrix of the type

$$\begin{vmatrix} 0 & 0 & 0 & 0 & a & 0 \\ 0 & 0 & 0 & a & b & d \\ 0 & 0 & 0 & 0 & f & e \\ 0 & \bar{a} & 0 & 0 & 0 & 0 \\ \bar{a} & \bar{b} & \bar{f} & 0 & 0 & 0 \\ 0 & \bar{d} & \bar{e} & 0 & 0 & 0 \end{vmatrix}.$$

From these examples the general form of C is clear.

Now $\sum c_{ij}x_i\bar{x}_j$ is what $\sum \epsilon_{ik}x_i\bar{x}_k$ becomes when A is transformed into N ; and therefore the matrix of C considered as a determinant does not vanish. But this is readily seen to be impossible unless the complex invariant-factors of C are paired as stated in the above theorem.

3. The quasi-Hermitian substitution A when transformed into canonical form N becomes the direct product of substitutions of the form

$$\left. \begin{aligned} x_1' &= \alpha x_1 + x_2, & \dots, & & x_{s-1}' &= \alpha x_{s-1} + x_s, & x_s' &= \alpha x_s \\ y_1' &= \bar{\alpha} y_1 + y_2, & \dots, & & y_{s-1}' &= \bar{\alpha} y_{s-1} + y_s, & y_s' &= \bar{\alpha} y_s \end{aligned} \right\}$$

where α is not real, and of substitutions of the form

$$x_1' = \alpha x_1 + x_2, \quad \dots, \quad x_{s-1}' = \alpha x_{s-1} + x_s, \quad x_s' = \alpha x_s$$

where α is real.

Then we can choose the new variables x, y, X so that A becomes N and $\sum_i \epsilon_{ik} x_i \bar{x}_i$ becomes the sum of functions of the type

$$(x_1 \bar{y}_s + \bar{x}_1 y_s) + (x_2 \bar{y}_{s-1} + \bar{x}_2 y_{s-1}) + \cdots + (x_s \bar{y}_1 + \bar{x}_s y_1)$$

and

$$= (X_1 \bar{X}_s + X_2 \bar{X}_{s-1} + \cdots + X_{s-1} \bar{X}_2 + X_s \bar{X}_1)$$

respectively.

The proof of this statement is suppressed, since it is exactly similar to the proof of a similar theorem for symmetric substitutions published elsewhere.*

As in Proc. London Math. Soc., 2, XI (1911), pp. 98–100, we can show that when

$$(x_1 \bar{y}_s + \bar{x}_1 y_s) + (x_2 \bar{y}_{s-1} + \bar{x}_2 y_{s-1}) + \cdots + (x_s \bar{y}_1 + \bar{x}_s y_1)$$

is reduced by change of variables to the form

$$= z_1 \bar{z}_1 = z_2 \bar{z}_2 = z_3 \bar{z}_3 = \cdots$$

there are s positive and s negative signs; while when

$$X_1 \bar{X}_s + X_2 \bar{X}_{s-1} + \cdots + X_s \bar{X}_1$$

is reduced to this form, the number of negative and the number of positive signs are equal when s is even, and differ by unity when s is odd. It follows that a series of properties of quasi-unitary substitutions established by Loewy (Math. Annalen, 50 (1898), pp. 563, 564), are also properties of a quasi-Hermitian substitution. For instance:—"The unreal characteristic-roots of the quasi-Hermitian substitution A are not more than $2k'$ in number; k' being the smaller of the quantities k and $m - k$. If exactly $m - 2k'$ characteristic-roots are real, they correspond to linear invariant-factors."

" A cannot have more than k' invariant-factors which are not linear. If A has exactly k' such invariant-factors they are all of degree 2 or 3. If they are all of degree 3, every characteristic-root of A is real."

4. A relation between quasi-Hermitian and quasi-unitary substitutions similar to that between symmetric and orthogonal substitutions, and proved in the same way,† is the following:—

All quasi-Hermitian substitutions with given invariant-factors can be transformed by a quasi-unitary substitution into the same quasi-Hermitian substitution which is the direct product of substitutions each of which has a single invariant-factor $(\lambda - \alpha)^a$ where α is real, or a pair of invariant-

* Proc. London Math. Soc., 2, XII (1913), p. 94.

† Mess. Math. (1912), p. 146; Bôcher's Higher Algebra, p. 302.

factors $(\lambda - \alpha)^a$, $(\lambda - \bar{\alpha})^a$. Similarly for quasi-unitary substitutions transformed by quasi-unitary substitutions.

Example:—Find a quasi-Hermitian substitution with invariant-factors

$$(\lambda - \alpha)^2, \quad (\lambda - \bar{\alpha})^2.$$

Since

$$\begin{aligned} x_1\bar{x}_4 + x_2\bar{x}_3 + x_3\bar{x}_2 + x_4\bar{x}_1 &\equiv (x + \tfrac{1}{2}x_4)(\bar{x}_1 + \tfrac{1}{2}\bar{x}_4) + (x_2 + \tfrac{1}{2}x_3)(\bar{x}_2 + \tfrac{1}{2}\bar{x}_3) \\ &\quad - (x_2 - \tfrac{1}{2}x_3)(\bar{x}_2 - \tfrac{1}{2}\bar{x}_3) - (x_1 - \tfrac{1}{2}x_4)(\bar{x}_1 - \tfrac{1}{2}\bar{x}_4) \end{aligned}$$

the required substitution is $F^{-1}NF$, where N is the canonical substitution

$$x_1' = \alpha x_1 + x_2, \quad x_2' = \alpha x_2; \quad x_3' = \bar{\alpha} x_3 + x_4, \quad x_4' = \bar{\alpha} x_4$$

and F is

$$x_1' = x_1 + \tfrac{1}{2}x_4, \quad x_2' = x_2 + \tfrac{1}{2}x_3, \quad x_3' = x_2 - \tfrac{1}{2}x_3, \quad x_4' = x_1 - \tfrac{1}{2}x_4.$$

A similar process will find a quasi-Hermitian or symmetric substitution with any assigned invariant-factors.

5. If we are given any substitution A , there are substitutions permutable with A k -ply infinite in number, where k is known when the invariant-factors of A are given.* The problem suggests itself:—"To determine k if the substitutions permutable with A are limited in any way; if, for instance, they are orthogonal."

This problem can be solved in special cases. We have, for instance, the results:—

If a symmetric substitution A has α invariant-factors $(\lambda - \lambda_1)^a$, β invariant-factors $(\lambda - \lambda_1)^b$, γ invariant-factors $(\lambda - \lambda_1)^c$, \dots , where

$$a > b > c > \dots,$$

the orthogonal substitutions permutable with A are

$$\Sigma \tfrac{1}{2} \{ \alpha(\alpha - 1)a + \beta(3\beta - 1)b + \gamma(5\gamma - 1)c + \delta(7\delta - 1)d + \dots \} \text{-ply}$$

infinite in number; the summation being extended over each distinct characteristic-root of A .

If a quasi-Hermitian substitution A has ρ invariant-factors $(\lambda - \lambda_1)^r$ and $(\lambda - \bar{\lambda}_1)^r$, σ invariant-factors $(\lambda - \lambda_1)^s$ and $(\lambda - \bar{\lambda}_1)^s$, τ invariant-factors $(\lambda - \lambda_1)^t$ and $(\lambda - \bar{\lambda}_1)^t$, \dots , ($r > s > t > \dots$), and α invariant-factors $(\lambda - \lambda_0)^a$, β invariant factors $(\lambda - \lambda_0)^b$, γ invariant-factors $(\lambda - \lambda_0)^c$, \dots , ($a > b > c > \dots$), where λ_0 is real, the quasi-unitary substitutions permutable with A are

$$\begin{aligned} \{ \Sigma [\rho^2 r + \sigma(2\rho + \sigma)s + \tau(2\rho + 2\sigma + \tau)t + \dots] \\ + \Sigma \tfrac{1}{2} [\alpha(\alpha - 1)a + \beta(3\beta - 1)b + \gamma(5\gamma - 1)c + \dots] \} \text{-ply} \end{aligned}$$

* Mess. Math. (1911), p. 112.

Now the most general substitutions permutable with N will be

[illegible]

Operating with this on $\varphi_1(x, x) + \varphi_1(\xi, \xi) + \varphi_1(X, X)$ we get*

$$\sum_t \{ [\varphi_s(a_{t1}, a_{t1}) \cdot \varphi_1(x, x) + \varphi_s(a_{t2}, a_{t1}) \cdot \varphi_1(\xi, x) + \varphi_s(a_{t3}, a_{t1}) \cdot \varphi_1(X, x) + \varphi_s(a_{t1}, a_{t2}) \varphi_1(x, \xi) + \varphi_s(a_{t2}, a_{t2}) \cdot \varphi_1(\xi, \xi) + \varphi_s(a_{t3}, a_{t2}) \cdot \varphi_1(X, \xi) + \varphi_s(a_{t1}, a_{t3}) \cdot \varphi_1(x, X) + \varphi_s(a_{t2}, a_{t3}) \cdot \varphi_1(\xi, X) + \varphi_s(a_{t3}, a_{t3}) \cdot \varphi_1(X, X)] + [\varphi_{s-1}(a_{t1}, a_{t1}) \cdot \varphi_2(x, x) + \dots] + [\varphi_{s-2}(a_{t1}, a_{t1}) \cdot \varphi_3(x, x) + \dots] + \dots \} \quad (t = 1, 2, 3).$$

This must reduce to $\varphi_1(x, x) + \varphi_1(\xi, \xi) + \varphi_1(X, X)$.

Let $A_s, A_{s-1}, A_{s-2}, \dots$ be the matrices whose general elements are respectively $a_{ij\ s}, a_{ij\ s-1}, a_{ij\ s-2}, \dots$ ($i, j = 1, 2, 3$).

Then we have in turn $A_s A'_s = 1$, $A_s A'_{s-1}' + A_{s-1} A'_s = 0$, $A_s A'_{s-2}' + A_{s-1} A'_{s-1}' + A_{s-2} A'_s = 0$, \dots .

Hence firstly, A is orthogonal so that the quantities a_{ij} are functions of $\frac{1}{2} \cdot 3 \cdot 2$ independent quantities.[†]

Then, when the quantities a_{ijs} are fixed, the quantities $a_{ij,s-1}$ are functions of $\frac{1}{2} \cdot 3 \cdot 2$ independent quantities, since $A_s A_{s-1}' + A_{s-1} A_s' = 0$.

In fact, given any non-singular matrix A of degree m , we can always find a matrix B of degree m , such that $AB' + BA'$ is a given symmetric matrix S , in a $\frac{1}{2}m(m-1)$ -ply infinite number of ways. For take P any matrix whose elements p_{ij} are arbitrary if $j > i$, and whose elements p_{ij} are given by $S = P + P'$ when $i \leq j$. Then we may suppose $AB' = P$, $BA' = P'$; which gives B in terms of the $\frac{1}{2}m(m-1)$ arbitrary quantities p_{ij} ($j > i$).

Then when the quantities a_{ijs} , $a_{ij\ s-1}$ are fixed, the quantities $a_{ij\ s-2}$ are functions of $\frac{1}{2} \cdot 3 \cdot 2$ independent quantities, since $A_s A_{s-2}' + A_{s-1} A_{s-1}' + A_{s-2} A_s' = 0$. Continuing this process, we see that the required substitutions permutable with N are $\frac{1}{2} \cdot 3 \cdot 2 \cdot s$ -ply infinite in number.

* Proc. London Math. Soc., 2, XII (1913), p. 96

† Cayley, Crelle, XXXII (1846), p. 119, Collected Works, I, p. 332.